

Construction and Application of Recreational Haptic Feedback

INTRODUCTION

- Haptic feedback can be described as technology that utilizes force and tactile experience. It is an example of immersive technology that communicates information via touch (Ambalina 2020).
- Technical fields such as undersea welding, hazardous material management, and remote medical procedure employ simple haptic feedback systems to improve telepresence.
- In fields such as medical surgery, doctors can't have a high cognitive load (the amount of working memory a person can hold at one time) or else they risk an unintended slip-up in their task. Haptic devices such as ours reduce the cognitive load of the user, making it easier to focus and concentrate on their task.

OUR CHALLENGE

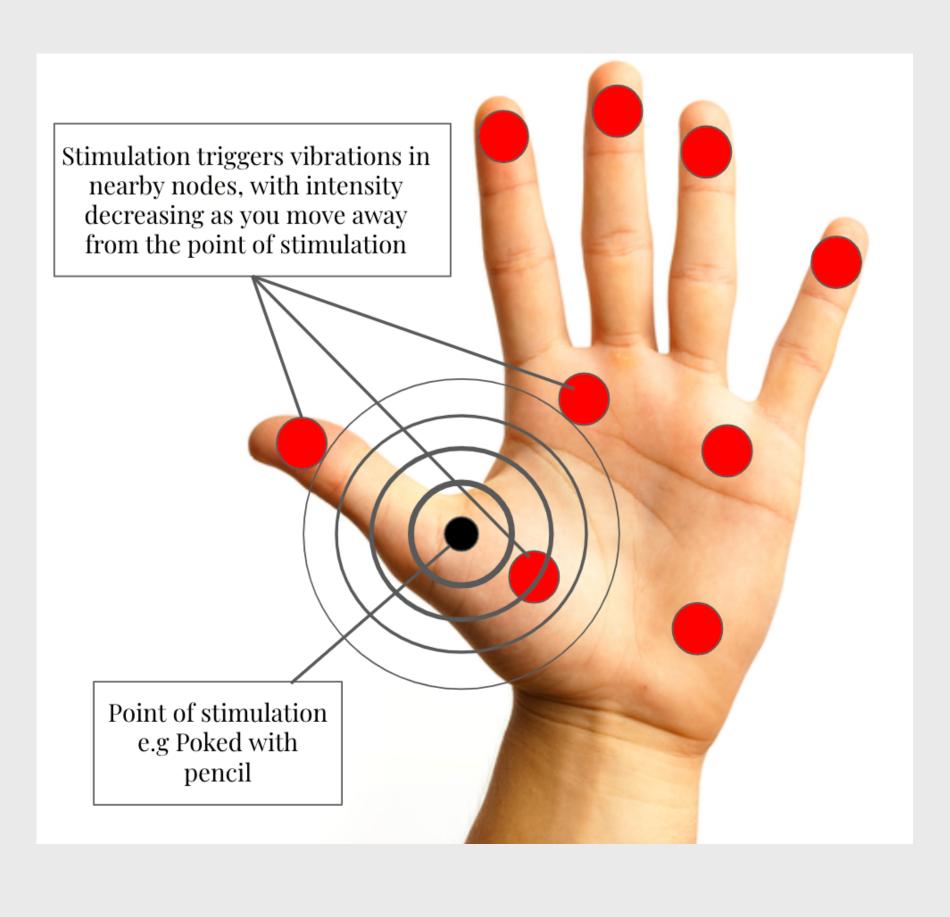
- The challenge is to have a cost-efficient and versatile haptic feedback product that can be used for a variety of applied purposes.

OUR SOLUTION

- Our solution is to apply cost-efficient and versatile components to a glove with vibrational feedback by utilization of Arduino and vibrational motors

CHECK OUT **OUR GLOVE!**





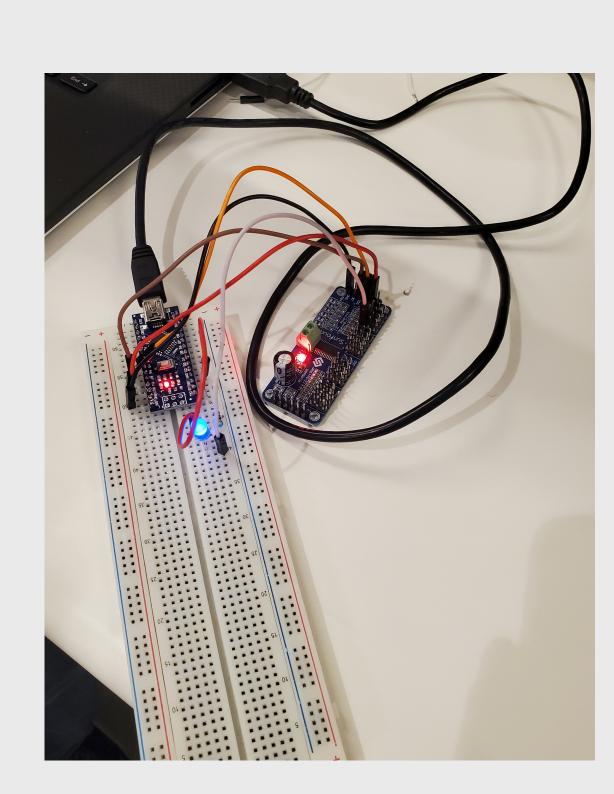
METHODOLOGY

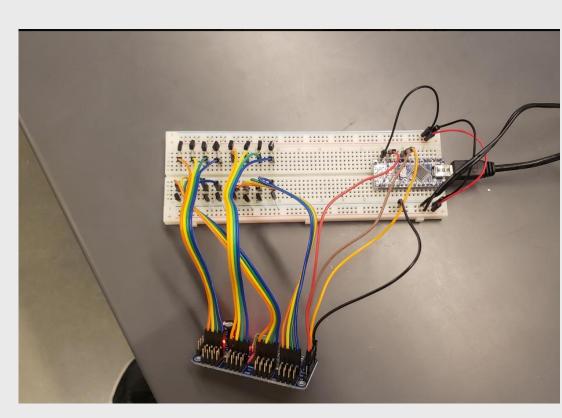
- Vibration motors
- Affixed to glove using hot glue & fabric
- Positions identified with the help of Professor

Anthony Lemus

- Coded on and driven by an Arduino Nano
- Servo Driver driving the motors via NPN transistors
- Altering the frequency and duty cycle of the PWM output alters the vibrational feedback strength

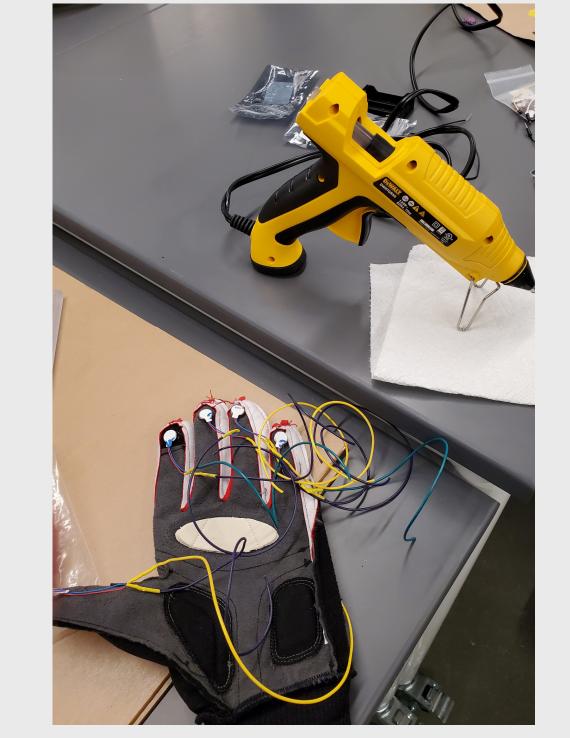






Circuit Board & Components





Glove Final Product (Above) & Glove Construction (Below)

AUTHORS

Alexa Zuch, Sarah Fieck, Justin Lee, Eric Chier, Spencer Lafferty

RESULTS /FINDINGS

- Wanted to incorporate TENS Unit or Balloon Acctuation systems for our glove.
- Found that the Vibrational System was much more applicable
- With these components, we have a successfully working recreational haptic feedback glove w/vibrational feedback

CONCLUSION

According to our findings, we found that a productive, cost effective, accessable, and versatile glove was a vibrational feedback-based glove using vibrational motors and an Arduino Nano. This system can be used for any number of applications where streamlined, lowcognitive-load haptic feedback is a necessity.

CITATIONS

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Dr. Mario Stipcic, and Dr. Aaron Harrison

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